Free boundaries and conservation equations in ice sheet models

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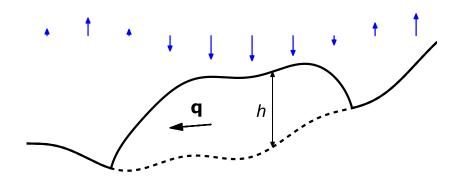
CESM LIWG 2015

Outline

- The problem I'm worried about:
 - Time-stepping free-boundary fluid layer models.

- Practical consequences:
 - Limitations to discrete conservation.
 - Need for weak numerical free boundary solutions.

A fluid layer in a climate

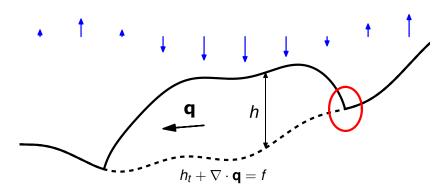


mass conservation PDE for a layer:

$$h_t + \nabla \cdot \mathbf{q} = \mathbf{f}$$

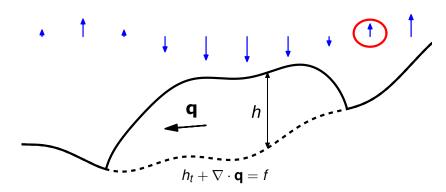
- h is a thickness: $h \ge 0$
- mass conservation PDE applies only where h > 0
- **q** is flow (vertically-integrated)
- source f is "climate"; f > 0 shown downward

A fluid layer in a climate: the troubles



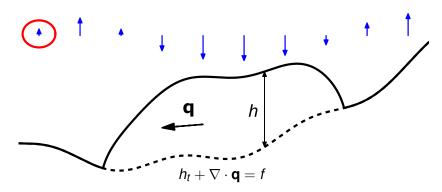
- h = 0 and what else at free boundary?
 - \circ shape at free boundary depends on both **q** and f
- f < 0 not "detected" by model where h = 0
 - how to do mass conservation accounting?
- $f \approx 0$ threshold behavior
 - h>0 as soon as f<0 switches to f>0

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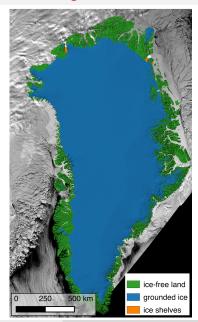
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A concern driven by practical modeling

- the icy region is nearly-fractal and disconnected
- currently in PISM*:
 - explicit time-stepping
 - free boundary by truncation
- want for PISM:
 - implicit time steps
 - better conservation accounting to user



^{*=} Parallel Ice Sheet Model, pism-docs.org

Examples



glaciers



tidewater marsh



ice shelves & sea ice

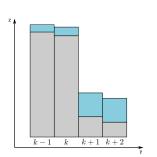


tsunami inundation

and subglacial hydrology, supraglacial runoff, surface hydrology, \dots

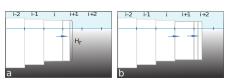
Anyone numerically-solved these problems before?

- yes, of course!
 - o generic result: ad hoc schemes near the free boundary

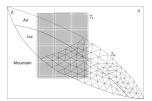


glacier ice on steep terrain

(Jarosch, Schoof, Anslow, 2013)



volume-of-fluid method at ice shelf fronts (Albrecht et al., 2011)



volume-of-fluid method at glacier surface (Jouvet et al 2008)

New goals

- I don't mind "if ...then ..." in my code, but I want to know what mathematical problem is behind it
 - maintaining code with those ad hoc schemes scares the #!*& out of me
- my goals:
 - o redefine the problem so free boundary is part of solution
 - tell the model user what is going on at the free boundary
 - find numerical schemes which automate the details

Numerical models *must* discretize time

$$h_t + \nabla \cdot \mathbf{q} = f$$
 \rightarrow $\frac{H_n - H_{n-1}}{\Delta t} + \nabla \cdot \mathbf{Q}_n = F_n$

- semi-discretize in time: $H_n(x) \approx h(t_n, x)$
- the new equation is a "single time-step problem"
 - a PDE in space where $H_n > 0$
 - o called the "strong form"
- details of flux \mathbf{Q}_n and source F_n come from time-stepping scheme

1D time-stepping examples

same:

- equation $\frac{H_n H_{n-1}}{\Delta t} + \nabla \cdot \mathbf{Q}_n = f$
 - climate f
 - bed shape
 - constrained-Newton scheme

how different are the fluxes \mathbf{Q}_n ?

1D time-stepping examples

$$\mathbf{Q}_n = v_0 H_n$$

hyperbolic
(constant velocity)

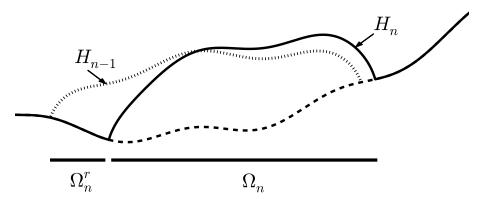
$$\mathbf{Q}_n = -\Gamma |H_n|^{n+2} \cdot |\nabla h_n|^{n-1} \nabla h_n$$
 highly-nonlinear diffusion

Subsets for time-stepping and conservation

- suppose H_n solves the single time-step problem
- define

$$\Omega_n = \{H_n(x) > 0\}$$

 $\Omega_n^r = \{H_n(x) = 0 \text{ and } H_{n-1}(x) > 0\} \leftarrow \text{retreat set}$



Reporting discrete conservation

• define:

$$M_n = \int_{\Omega} H_n(x) dx$$
 mass at time t_n

then

$$\Delta t \left(-\nabla \cdot \mathbf{Q}_{n} + F_{n}\right)$$

$$M_{n} - M_{n-1} = \int_{\Omega_{n}} H_{n} - H_{n-1} dx + \int_{\Omega_{n}'} 0 - H_{n-1} dx$$

$$= \Delta t \left(0 + \int_{\Omega_{n}} F_{n} dx\right) - \int_{\Omega_{n}'} H_{n-1} dx$$

new term:

$$R_n = \int_{\Omega_n^r} H_{n-1} dx$$
 retreat loss during step n

Reporting discrete conservation: *limitation*

- the retreat loss R_n is not balanced by the climate
 - R_n is caused by the climate, but we don't know a computable integral to balance it
- we must track three time series:
 - mass at time t_n : $M_n = \int_{\Omega} H_n(x) dx$
 - o climate (e.g. surface mass bal.) over current fluid-covered region:

$$C_n = \Delta t \int_{\Omega_n} F_n dx \approx \int_{t_{n-1}}^{t_n} \int_{\Omega_n} f(t, x) dx dt$$

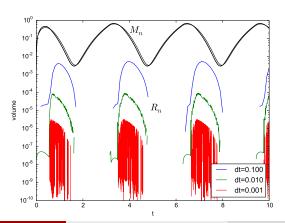
• retreat loss during time step: $R_n = \int_{\Omega^r} H_{n-1} dx$

$$R_n = \int_{\Omega^r} H_{n-1} dx$$

now it balances:

$$M_n = M_{n-1} + C_n - R_n$$

Reporting discrete conservation: $R_n \to 0$ as $\Delta t \to 0$



Weak form incorporates constraint

define:

$$\mathcal{K} = \left\{ v \in \mathit{W}^{1,p}(\Omega) \,\middle|\, v \geq 0
ight\} = \mathsf{admissible thicknesses}$$

• we say $H_n \in \mathcal{K}$ solves the weak single time-step problem if

$$\int_{\Omega} H_n(v - H_n) - \Delta t \, \mathbf{Q}_n \cdot \nabla (v - H_n) \ge \int_{\Omega} \left(H_{n-1} + \Delta t \, F_n \right) (v - H_n)$$

for all $v \in \mathcal{K}$

- derive this variational inequality from:
 - the strong form and
 - integration-by-parts and
 - \diamond arguments about $H_n = 0$ areas

Weak solves strong, and it gives more info

- assume $\mathbf{Q}_n = 0$ when $H_n = 0$
 - this means **Q**_n describes a *layer*
- assume $H_n \in \mathcal{K}$ solves weak single time-step problem
- then
 - **1** PDE applies on the set where $H_n > 0$:

$$\frac{H_n - H_{n-1}}{\Delta t} + \nabla \cdot \mathbf{Q}_n = F_n$$

2 information on the set where $H_n = 0$:

$$H_{n-1} + \Delta t F_n \leq 0$$

 this means "mass balance was negative enough during time step to remove old thickness"

Numerical solution of the weak problem

the weak single time-step problem:

- is nonlinear because of constraint (even for \mathbf{Q}_n linear in H_n)
- can be solved by a Newton method modified for constraint
 - reduced set method
 - semismooth method
- scalable implementations are in PETSc 3.5
 - o see "SNESVI" object

Summary

- layer flow model has conservation eqn. $h_t + \nabla \cdot \mathbf{q} = f$
 - o long time steps wanted, but this is a free-boundary problem ...
- claim: exact discrete conservation requires tracking retreat loss
 - in addition to computable integrals of climate
 - o it only disappears in $\Delta t \rightarrow 0$ limit
- suggestions:
 - *include* constraint on thickness: *h* > 0
 - pose single time-step problem weakly as variational inequality
 - solve it numerically by constrained-Newton method
- these are agnostic claims/suggestions, with respect to:
 - o form of the flux q
 - o spatial discretization paradigm (i.e. finite diff./volume/element)