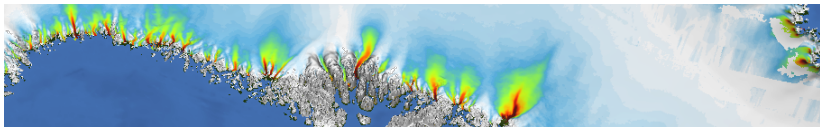


# Implicit time-stepping for ice sheets

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# Outline

problem, goals, and models

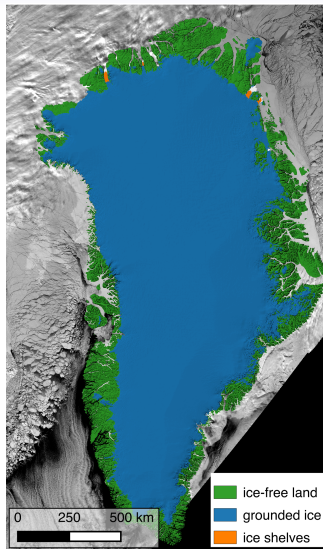
semi-discretizations

solving the equations for one time step

some early results

# ice sheet flows and their boundaries

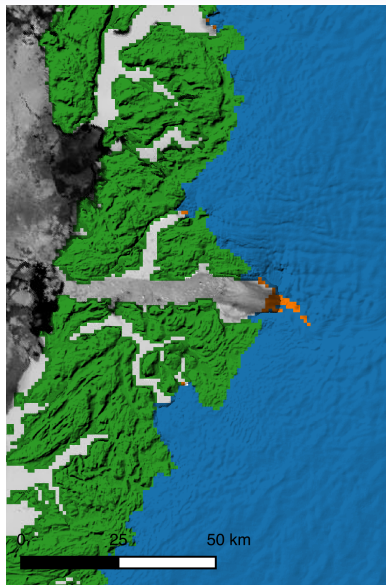
- nearly-fractal free boundaries
  - location determined by flow, topography, and atmosphere/ocean inputs
- large fraction of the boundary: grounded margins
- surface slope is discontinuous at grounded margins



PISM mask, by A. Aschwanden

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Taku Glacier, Alaska, by M. Truffer

## computational goal: long-time, high-res runs

- my goal:

*routinely simulate ice sheets on their natural time scales (ice age cycles  $\gtrsim 10^5$  years) at resolutions where bedrock bumps, outlet glaciers, ice streams, and grounding lines are resolved ( $\lesssim 500$  m)*

- PISM (Parallel Ice Sheet Model) not there yet ... either long-time *OR* high-res
- some concerns:
  1. stress-balance solves expensive
    - if time steps are short then stress balance is a lot of work
    - ... energy conservation (temperature and basal melt) too!
  2. evolution of ice thickness  $H(t, x, y)$  is diffusive ... thus stiff
    - because ice flows downhill
  3. ice margins are low-regularity
    - 2 reasons: (i) constraint  $H \geq 0$  and (ii) degeneracy
  4. bedrock is steep

## a performance model

- grid spacing  $h = \Delta x = \Delta y$  in 2D
  - (degrees of freedom)  $= O(h^{-2})$
- time step limited by stability or accuracy:

$$\Delta t \leq O(h^q)$$

- $q = 2$  for conditionally-stable explicit schemes on diffusions
  - accuracy alone suggests  $0 < q < 1$  ? ... a scientific question?
- solution at one time step:
  - $N(h)$  Newton iterations
  - $K(h)$  (preconditioned) Krylov steps per Newton
- cost of computation on  $\Omega \times [0, T]$ :
$$C(h) = (\text{number of steps}) \cdot (\text{iterations per step}) \cdot (\text{cost of 1 residual})$$
$$= O(h^{-q}) \cdot N(h) \cdot K(h) \cdot O(h^{-2})$$
  - explicit:  $C(h) = O(h^{-2}) \cdot 1 \cdot 1 \cdot O(h^{-2}) = O(h^{-4})$  ← beat this!

## ice sheet models

- fixed computational domain  $\Omega \subset \mathbb{R}^2$  where inputs  $b =$  (bed elevation) and  $m =$  (mass balance) are given

- $\Omega$  is only partly-covered by ice

- shallow, possibly-hybrid, thickness-based

$$H, \mathbf{u} = (u, v)$$

$$H_t + \nabla \cdot (-D\nabla H + \bar{\mathbf{u}}H) = m(x, t) \quad \text{mass conservation}$$

$$\mathcal{L}(\mathbf{u}, H) = 0 \quad \text{shallow stress balance}$$

- also: Stokes, surface-elevation-based

$$s, \mathbf{u} = (u, v, w)$$

$$s_t + \mathbf{u}|_s \cdot (s_x, s_y, -1) = m(x, t) \quad \text{surface kinematical}$$

$$\nabla \cdot \mathbf{u} = 0 \quad \text{incompressibility}$$

$$\mathcal{L}(\mathbf{u}, s) = 0 \quad \text{Stokes stress balance}$$

- notation & assumptions:

- $H$  thickness,  $s$  surface elevation,  $\mathbf{u}$  velocity
  - $D = D(H, |\nabla s|)$  is SIA diffusivity (nonlinear & degenerate)
  - conservation of energy ignored for simplicity
  - Eulerian, fixed grid (structured or not)



## semi-discretize in space

- method of lines (MOL)
  - *can you hand the thing to an ODE solver?*
- well-known: MOL for slow fluids is a DAE problem

$$\dot{H} = f(H, \mathbf{u}, t) \quad \text{mass conservation}$$

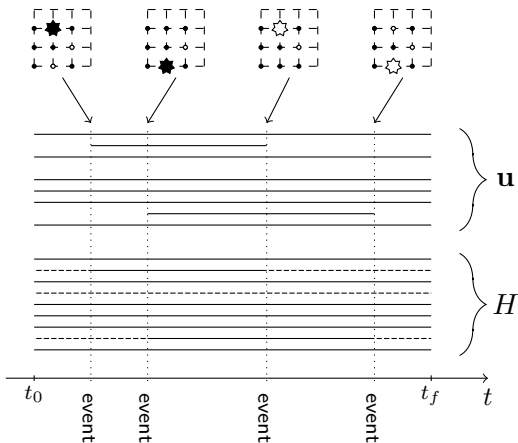
$$0 = g(H, \mathbf{u}) \quad \text{momentum conservation}$$

- *isn't implicit time-stepping required for DAEs anyway?*
- velocity variables only exist at positive-thickness locations  $i$ :

$$\mathbf{u}_i \text{ exists} \quad \Longleftarrow \quad H_i > 0$$

- thus ODE solver must handle *events* like these?:
  - ice disappears during time step:  $H_i(t) > 0 \rightarrow H_i(t + \Delta t) = 0$
  - ice appears during time step:  $H_i(t) = 0 \rightarrow H_i(t + \Delta t) > 0$

## MOL+events cannot scale



- at each event the ice velocity dimension changes
- ice sheet margins nearly fractal, so *a lot* of events to handle
- re-meshing at *every* event probably won't scale

## semi-discretize in time

- semi-discretize in time *for understanding*
- consider a single backward Euler time-step
  - better time-stepping later
- hybrid equations become (notation:  $H = H_{\text{new}}$ ,  $\mathbf{u} = \mathbf{u}_{\text{new}}$ ):

$$H - H_{\text{old}} + \Delta t \nabla \cdot (-D \nabla H + \mathbf{u} H) = \Delta t m$$
$$\mathcal{L}(\mathbf{u}, H) = 0$$

## single time-step problem for mass conservation

- solve for  $H$  **subject to**  $H \geq 0$ :

$$H - H_{\text{old}} + \Delta t \nabla \cdot \mathbf{q} = \Delta t m$$

- where  $\mathbf{q} = -D\nabla H + \mathbf{u}H$
- note:  $D = D(H, |\nabla s|) \rightarrow 0$  at margins
- make rigorous two ways:
  - variational inequality (VI)

$$\int_{\Omega} (H - H_{\text{old}} - \Delta t m)(\eta - H) - \Delta t \mathbf{q} \cdot \nabla(\eta - H) \geq 0, \quad \forall \eta \geq 0$$

- nonlinear complementarity problem (NCP)

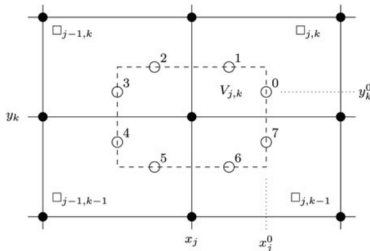
$$F(H) = H - H_{\text{old}} + \Delta t \nabla \cdot \mathbf{q} - \Delta t m \geq 0$$

$$H \geq 0$$

$$HF(H) = 0$$

## solving the equations

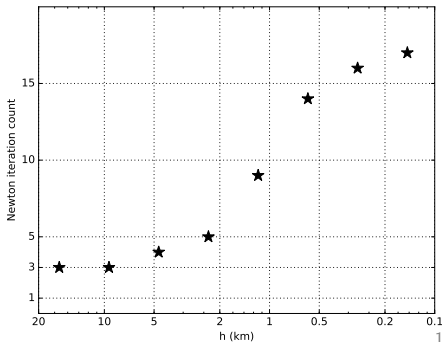
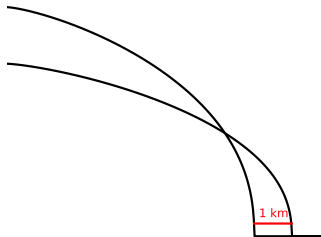
- discretize in space:
  - e.g.  $M^* = (Q^1 \text{ elements and finite volume weak form } \int_V)$  Bueler 2016



- wrote small PETSc code for mass conservation problem:
  - MOL using  $M^*$
  - tells TS object which part is stiff:  $F(H_t, H) = G(t, H)$ 
    - $F = H_t + \nabla \cdot \mathbf{q}$  and  $G = m$
  - allows any implicit or IMEX time-stepping
- equations at each time step are solved with
  - NCP-adapted (“reduced-space” or “semi-smooth”) Newton
    - \* `-snes_type vinewton{rs|ss}ls` Benson & Munson 2006
  - + Krylov solver + preconditioning

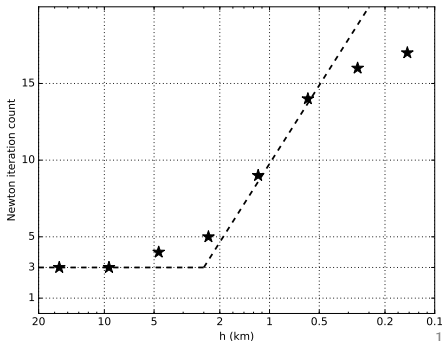
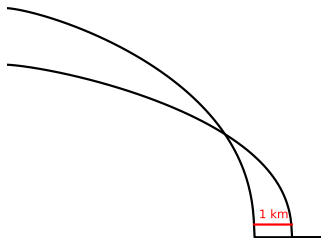
## margin advance experiment: Newton iterations

- consider a single 10-year beuler time step
- of a Greenland-sized radial ice sheet
  - flat bed,  $m = 0$
  - margin advance 975 m
- reduced-space Newton solver sees Jacobian in inactive variables only
  - states are admissible
  - dimension changes at each Newton step
- on fine grids ( $\lesssim 1$  km) the number of Newton iterations is proportional to margin motion divided by  $\Delta x$



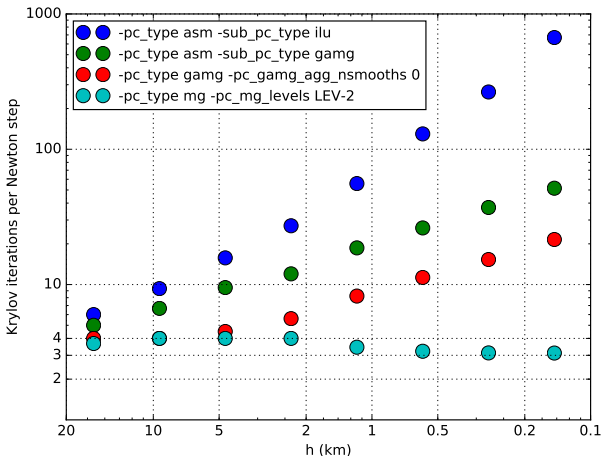
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## margin advance experiment: preconditioners

- fixed MPI rank = 64
- compare preconditioners:  
-snes\_type vinewtonrsls -ksp\_type gmres -pc\_type X
- Krylov iterations per Newton step:

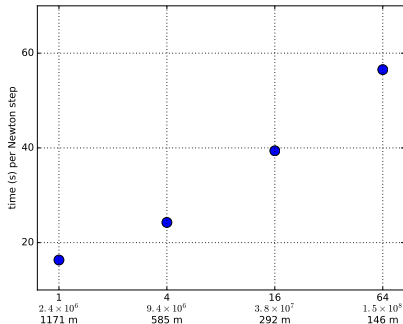




## margin advance experiment: weak scaling?

- very preliminary weak-scaling evidence
  - ranks 1, 4, 16, 64
  - fixed d.o.f. per process:  $2.4 \times 10^6$
  - `-pc_type mg`
- time per Newton step:

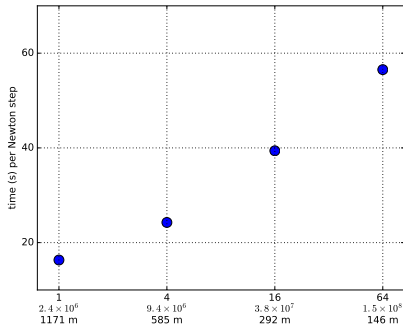
*... should be flat!*



- the good news:  $\Delta t / \Delta t_{FE} = 9 \times 10^4$  on finest grid

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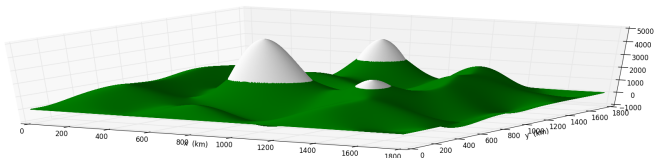
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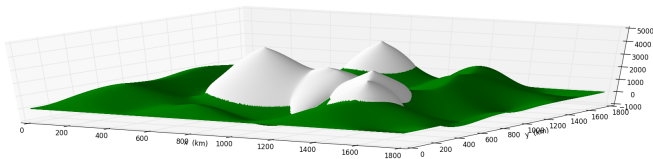
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## example: 50ka run with topography and sliding

$t = 0$  a



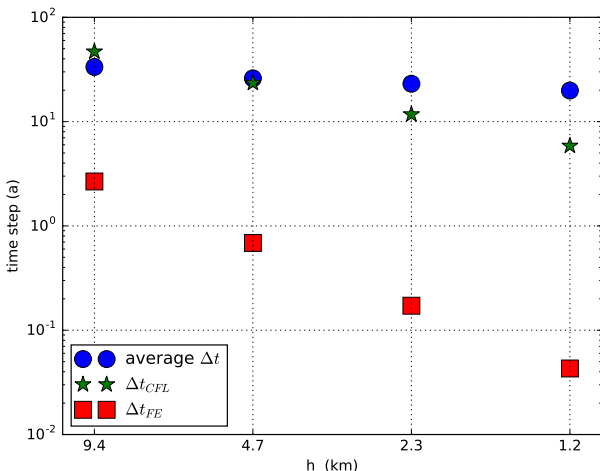
$t = 50$  ka



- solve:  $H_t + \nabla \cdot \mathbf{q} = m$  where  $\mathbf{q} = -D\nabla H + \mathbf{u}H$ 
  - imposed “sliding”  $\mathbf{u}(x, y)$
  - elevation-dependent accumulation/ablation  $m = m(s)$

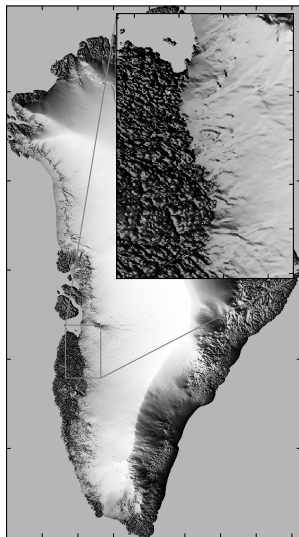
## 50ka run: time-stepping performance

- ARKIMEX(3): adaptive Runge-Kutta implicit/explicit 3rd-order (3 stage) time-stepping
- at least three nonlinear solves per time step



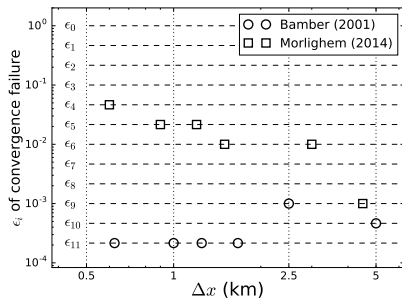
## example: Greenland ice sheet $\Delta t = \infty$

- steady geometry  $H(x, y)$  of the Greenland ice sheet
  - given  $m(x, y)$  and  $b(x, y)$
- Bueler 2016, J. Glaciol.
- one  $\Delta t = \infty$  step
  - 900 m structured grid
  - $7 \times 10^6$  d.o.f.
- *but* Newton convergence suffers from bed roughness



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## summary

- recommendations for implicit time-stepping of thickness-based mass conservation:
  - enforce  $H \geq 0$  as NCP or VI
  - use reduced-space solver which has admissible states for stress balance solution
  - use geometric multigrid (?)
  - result:  $> 10^5 \Delta t_{FE}$  achievable
- some limitations:
  - extra Newton steps needed to move margins  $x$  grid spaces
  - bed roughness eventually limits Newton solver convergence
  - calving and front-melting not addressed in this framework
  - ...yet
- wiser now? ...if I were to start over with PISM:

```
mpiexec -n N newpism -da_refine M \  
-ts_type arkimex -snes_type vinewtonrsls -pc_type mg
```