

Free-boundary problems in models of the cryosphere

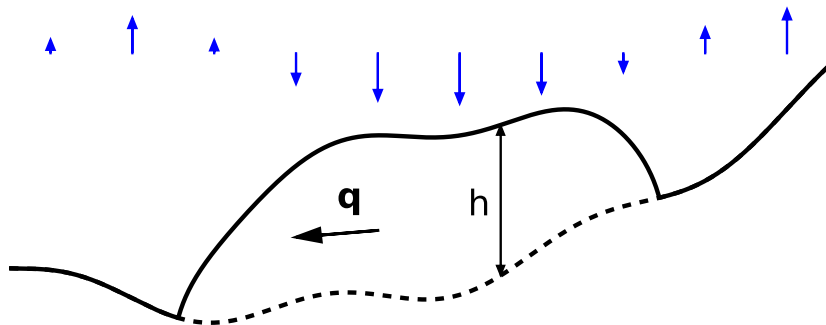
Ed Bueler

Dept of Mathematics and Statistics, and Geophysical Institute
University of Alaska Fairbanks
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Stanford University

- 1 The problem I'm worried about:
 - time-stepping free-boundary fluid layer models
- 2 Practical conclusions:
 - approach I: semi-discretize in time
 - approach II: each time-step is weakly-posed free-bdry problem
 - newly-available numerical tools
 - new (?) limitations to discrete conservation

A fluid layer in a climate

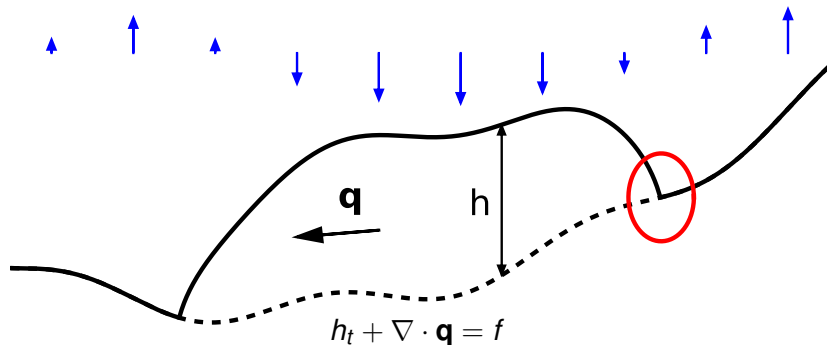


- mass conservation PDE for a layer:

$$h_t + \nabla \cdot \mathbf{q} = f$$

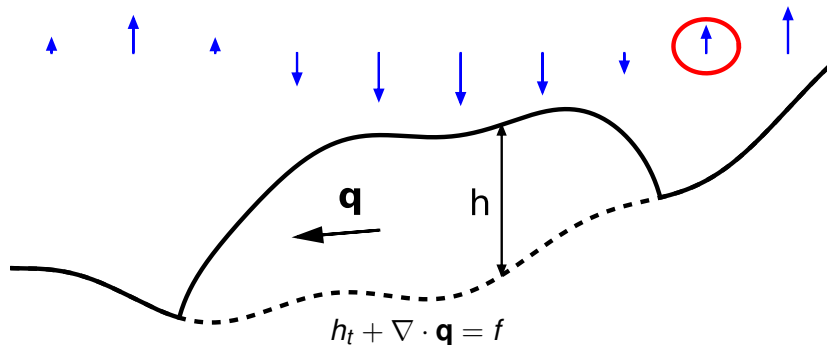
- h is a thickness: $h \geq 0$
- mass conservation PDE applies only where $h > 0$
- \mathbf{q} is flow (vertically-integrated)
- source f is “climate”; $f > 0$ shown downward

A fluid layer in a climate: *the troubles*



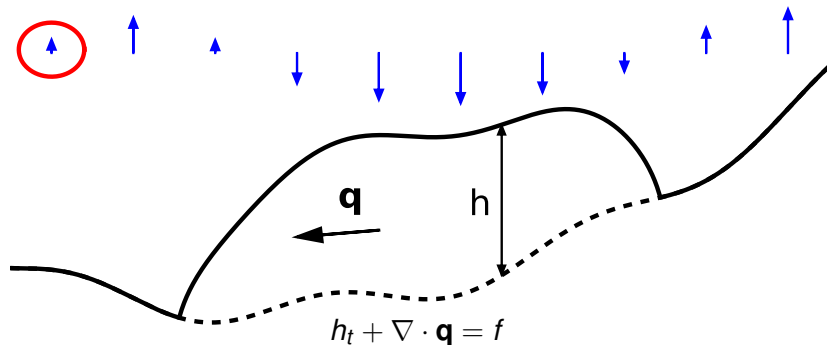
- $h = 0$ and what else at free boundary?
 - shape at free boundary depends on both \mathbf{q} and f
- $f < 0$ not “detected” by model where $h = 0$
 - how to do mass conservation accounting?
- $f \approx 0$ threshold behavior
 - $h > 0$ as soon as $f < 0$ switches to $f > 0$

A fluid layer in a climate: *the troubles*



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Examples



glaciers



ice shelves & sea ice



tidewater marsh

and also surface hydrology, subglacial hydrology, . . .

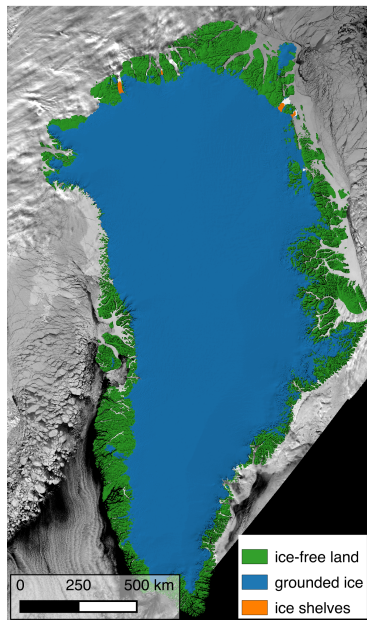


tsunami inundation

I'm driven here by practical modeling: ice sheets

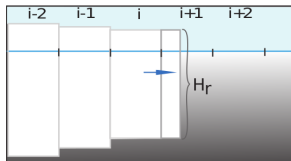
- the icy region is nearly-fractal and disconnected
- currently in our ice sheet model*:
 - explicit time-stepping
 - free boundary by truncation
- want for our model:
 - long implicit time steps
 - better conservation accounting to user

*Parallel Ice Sheet Model, pism-docs.org

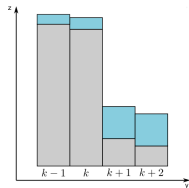


Has anyone solved these problems before?

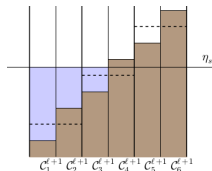
- yes, of course!
- generic result: *ad hoc* schemes near the free boundary



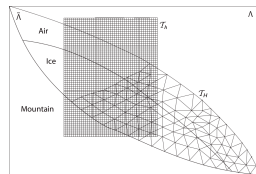
volume-of-fluid method at ice shelf fronts
(Albrecht et al, 2011)



glacier ice on steep terrain
(Jarosch, Schoof, Anslow, 2013)



tsunami run-up on shore
(LeVeque, George, Berger, 2011)



volume-of-fluid method at glacier surface
(Jouvet et al 2008)

Approach I: semi-discretize in time

$$h_t + \nabla \cdot \mathbf{q} = f \quad \rightarrow \quad \frac{H_n - H_{n-1}}{\Delta t} + \nabla \cdot \mathbf{Q}_n = F_n$$

- semi-discretize in time: $H_n(x) \approx h(t_n, x)$
- the new equation is strong form **single time-step problem**
 - a PDE in space where $H_n > 0$
 - details of flux \mathbf{Q}_n and source F_n come from time-stepping scheme
 - ★ e.g. θ -methods or RK

1D time-stepping examples (and my \mathbf{q} -agnosticism)

same:

- equation

$$\frac{H_n - H_{n-1}}{\Delta t} + \nabla \cdot \mathbf{Q}_n = f$$

- BEuler time-step
- climate f
- bed shape
- constraint-respecting
Newton scheme

top:

$$\mathbf{Q}_n = v_0 H_n$$

hyperbolic advection with
constant velocity

bottom:

$$\mathbf{Q}_n = -\Gamma |H_n|^{n+2} \cdot |\nabla s_n|^{n-1} \nabla s_n$$

nonlinear degenerate
diffusion

Approach II: weak form incorporates $H_n \geq 0$ constraint

- define:

$$\mathcal{K} = \left\{ v \in W^{1,p}(\Omega) \mid v \geq 0 \right\} = \text{admissible thicknesses}$$

- we say $H_n \in \mathcal{K}$ solves the weak single time-step problem if

$$\int_{\Omega} H_n (v - H_n) - \Delta t \mathbf{Q}_n \cdot \nabla (v - H_n) \geq \int_{\Omega} (H_{n-1} + \Delta t F_n) (v - H_n)$$

for all $v \in \mathcal{K}$

- derive this *variational inequality* (VI) from:
 - ◊ integration-by-parts on strong form
 - ◊ thought about $H_n = 0$ areas

Weak solves strong; gives more info

- assume $\mathbf{Q}_n = 0$ when $H_n = 0$
 - this means \mathbf{Q}_n describes a *layer*
- if $H_n \in \mathcal{K}$ solves weak single time-step problem (VI) then
 - PDE applies on the set where $H_n > 0$ (interior condition):

$$\frac{H_n - H_{n-1}}{\Delta t} + \nabla \cdot \mathbf{Q}_n = F_n$$

- plus inequality on the set where $H_n = 0$:

$$H_{n-1} + \Delta t F_n \leq 0$$

- ★ “climate negative enough during time step to remove old thickness”

Alternative weak formulation: NCP

- NCP = nonlinear complementarity problem
- abstractly, NCP is:

- given differentiable map $\mathbf{F} : \mathbb{R}^n \rightarrow \mathbb{R}^n$
- solve

$$\mathbf{x} \geq 0, \quad \mathbf{F}(\mathbf{x}) \geq 0, \quad \mathbf{x}^\top \mathbf{F}(\mathbf{x}) = 0$$

- our case:
 - ∞ dimensions with m.c. equation $h_t + \nabla \cdot \mathbf{q} = f$
 - $\mathbf{x} = H_n$ and $\mathbf{F}(\mathbf{x}) =$ (residual from discrete-time m.c. eqn.)
- in finite dimensions we have VI \leftrightarrow NCP equivalence:

$$\langle \mathbf{F}(\mathbf{x}), \mathbf{y} - \mathbf{x} \rangle \geq 0 \quad \forall \mathbf{y} \in \mathcal{K} \quad \Longleftrightarrow \quad \text{NCP}$$

Numerical solution of the weak problem

the weak single time-step problem:

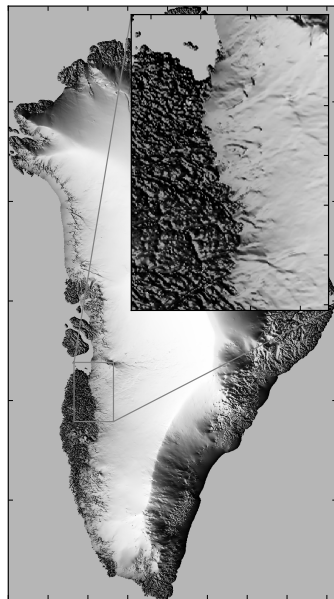
- is nonlinear because of constraint (even for \mathbf{Q}_n linear in H_n)
- can be solved by a Newton method modified for constraint
- scalable implementations are in PETSc* 3.5+
 - see “SNESVI” object
 - for NCP there are two implementations (Benson & Munson, 2006):
 - ★ reduced-set (active-set) method
 - ★ semismooth method

*Portable Extensible Toolkit for Scientific computation, www.mcs.anl.gov/petsc

Example: Greenland ice sheet

- given steady climate and bedrock elevations, what is shape of Greenland ice sheet?
 - climate = “surface mass balance”
= precipitation – runoff-from-melt
- assume simplest reasonable dynamics: non-sliding shallow ice approximation
- solve VI/NCP weak problem
 - steady state ($\Delta t \rightarrow \infty$)
 - reduced-set Newton method
 - 900 m structured grid
 - Q^1 FEs in space
 - $N = 7 \times 10^6$ d.o.f.

(Bueler, submitted to J. Glaciol.)

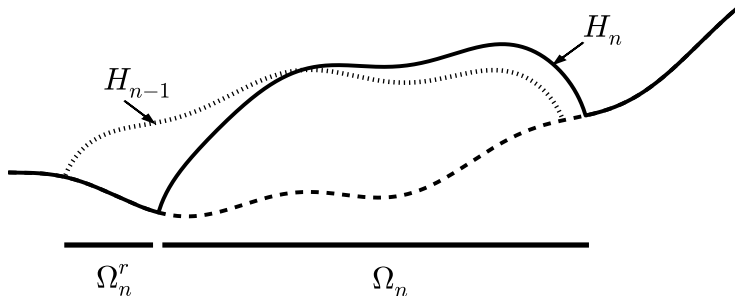


Conservation reporting: subsets

- suppose H_n solves the single time-step problem
- define

$$\Omega_n = \{H_n(x) > 0\}$$

$$\Omega_n^r = \{H_n(x) = 0 \text{ and } H_{n-1}(x) > 0\} \quad \leftarrow \text{retreat set}$$



Conservation reporting: time-series

- define:

$$M_n = \int_{\Omega} H_n(x) dx \quad \text{mass at time } t_n$$

- then

$$\Delta t (-\nabla \cdot \mathbf{Q}_n + F_n)$$

$$\begin{aligned} M_n - M_{n-1} &= \int_{\Omega_n} \boxed{H_n - H_{n-1}} dx + \int_{\Omega_n^r} 0 - H_{n-1} dx \\ &= \Delta t \left(0 + \int_{\Omega_n} F_n dx \right) - \int_{\Omega_n^r} H_{n-1} dx \end{aligned}$$

- new term:

$$R_n = \int_{\Omega_n^r} H_{n-1} dx \quad \text{retreat loss during step } n$$

Conservation reporting: *limitation*

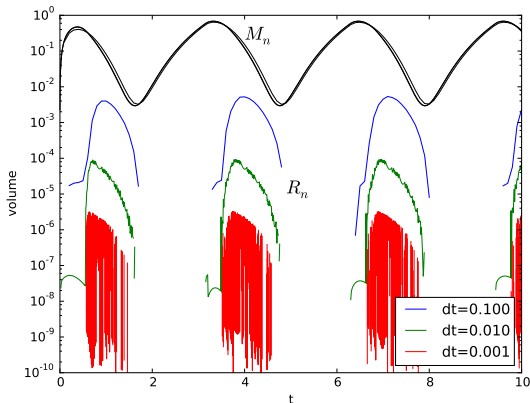
- the retreat loss R_n is not balanced by the climate
 - R_n is *caused* by the climate, but we don't know a computable integral of climate F_n to balance it
- we must track **three** time series:
 - mass at time t_n : $M_n = \int_{\Omega} H_n(x) dx$
 - climate (e.g. surface mass bal.) over current fluid-covered region:

$$C_n = \Delta t \int_{\Omega_n} F_n dx \quad \approx \int_{t_{n-1}}^{t_n} \int_{\Omega_n} f(t, x) dx dt$$

- retreat loss during time step: $R_n = \int_{\Omega_n} H_{n-1} dx$
- now it balances:

$$M_n = M_{n-1} + C_n - R_n$$

Reporting discrete conservation: $R_n \rightarrow 0$ as $\Delta t \rightarrow 0$



Summary

consider layer flow model $h_t + \nabla \cdot \mathbf{q} = f$ subject to signed climate f and where h is layer thickness

- goals/issues:

- long time steps wanted
- models have been limited by free-boundary lack-of-clarity

- approach:

- include constraint on thickness: $h \geq 0$
- consider discrete-time problem before doing FEM/FVM/etc.
- pose single time-step problem weakly as VI or NCP
- solve by scalable constrained-Newton method (PETSc)

- new (?) result:

- discrete conservation requires tracking retreat-loss time-series
 - ★ in addition to climate input during time step